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## NTE1628 Integrated Circuit Bi-Directional Motor Driver

**Description:**

The NTE1628 is a Bi-Directional Motor Driver in a 9-lead SIP type package consisting of a full bridge power driver and is designed for DC motor control.

**Features:**

- Wide Operating Voltage Range ( $V_{CC} = 4V$  to  $16V$ )
- Direct Drive Capability by TTL, PMOS, and CMOS IC Outputs
- Low Output Saturation Voltage (Large Voltage Across Motor)
- Built-In Clamp Diode
- Large Output Current Drive ( $I_O(\max) = \pm 1.2A$ )
- Braking Mode Input

**Application:**

Commercial Audio Equipment such as Tape Recorder, Radio Cassette Recorder, and VCR

**Function:**

The NTE1628, full bridge motor driver, has the logic circuitry and non-darlington power drivers for bidirectional control of DC motors operating at currents up to 1.2A. A braking mode is achieved by switching both inputs high for ease of motor control. Both of the separated power supplies for the logic circuitry and the drivers are usable for motor speed control.

**Absolute Maximum Ratings:** ( $T_A = +25^\circ C$ , Unless otherwise noted)

Supply Voltage,

$V_{CC(1)}$  .....  $-0.5$  to  $+16V$

$V_{CC(2)}$  (With an external heat sink) .....  $-0.5$  to  $+20V$

Driver Supply Voltage,  $V_{CC'}$  .....  $-0.5$  to  $+16V$

Input Voltage,  $V_I$  .....  $0$  to  $V_{CC}$

Output Voltage,  $V_O$  .....  $-0.5V$  to  $V_{CC'} + 2.5V$

Peak Output Current ( $t = 10ms$ , Repetition Cycle  $0.2Hz$  Max),  $I_{O\ MAX}$  .....  $\pm 1.2A$

Continuous Output Current,

$I_O(1)$  .....  $\pm 330A$

$I_O(2)$  (With an external heat sink) .....  $\pm 500mA$

Power Dissipation ( $T_A = +75^\circ C$ ),  $P_d$  .....  $1.15W$

Operating Ambient Temperature Range,  $T_{opr}$  .....  $-10^\circ$  to  $+75^\circ C$

Storage Temperature Range,  $T_{stg}$  .....  $-55^\circ$  to  $+120^\circ C$

**Recommended Operating Conditions:** ( $T_A = +25^\circ\text{C}$  unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Supply Voltage	$V_{CC}$		4	12	15	V
Continuous Output Current	$I_O$		-	-	$\pm 300$	mA
“H” Input Voltage	$V_{IH}$		2	-	$V_{CC}$	V
“L” Input Voltage	$V_{IL}$		0	-	0.4	V
Motor Braking Interval	$t_B$		100	-	-	ms

**Electrical Characteristics:** ( $T_A = +25^\circ\text{C}$  unless otherwise specified)

Parameter	Symbol	Test Conditions		Min	Typ	Max	Unit	
Output Leakage Current	$I_{O(\text{leak})}$	$V_{CC} = V_{CC'} = 20\text{V}$ , $V_{11} = V_{12} = 0\text{V}$	$V_O = 20\text{V}$	-	-	100	$\mu\text{A}$	
			$V_O = 0\text{V}$	-	-	-100	$\mu\text{A}$	
Output Saturation Voltage, High	$V_{OH(1)}$	$V_{CC} = V_{CC'} = 12\text{V}$	$V_{11} = 2\text{V}$ , $V_{12} = 0\text{V}$	$I_{OH(1)} = -300\text{mA}$	10.8	11.2	-	V
				$I_{OH(1)} = -500\text{mA}$	10.7	11.1	-	V
	$V_{OH(2)}$		$V_{11} = 0\text{V}$ , $V_{12} = 2\text{V}$	$I_{OH(1)} = -300\text{mA}$	10.8	11.2	-	V
				$I_{OH(1)} = -500\text{mA}$	10.7	11.1	-	V
Output Saturation Voltage, Low	$V_{OL(1)}$	$V_{CC} = V_{CC'} = 12\text{V}$	$V_{11} = 0\text{V}$ , $V_{12} = 2\text{V}$	$I_{OL(1)} = 300\text{mA}$	-	0.18	0.5	V
				$I_{OL(1)} = 500\text{mA}$	-	0.3	0.65	V
			$V_{11} = V_{12} = 2\text{V}$	-	0.3	0.65	V	
	$V_{OL(2)}$		$V_{11} = 2\text{V}$ , $V_{12} = 0\text{V}$	$I_{OL(1)} = 300\text{mA}$	-	0.18	0.5	V
				$I_{OL(1)} = 500\text{mA}$	-	0.3	0.65	V
			$V_{11} = V_{12} = 2\text{V}$	-	0.3	0.65	V	
Input Current, High	$I_{IN(1)}$	$V_{CC} = V_{CC'} = 12\text{V}$ , $V_{11} = 2\text{V}$ , $V_{12} = 0\text{V}$		70	-	200	$\mu\text{A}$	
	$I_{IN(2)}$	$V_{CC} = V_{CC'} = 12\text{V}$ , $V_{11} = 0\text{V}$ , $V_{12} = 2\text{V}$		70	-	200	$\mu\text{A}$	
Supply Current	$I_{CC}$	$V_{CC} = V_{CC'} = 15\text{V}$	$V_1 = 2\text{V}$ , $V_2 = 0\text{V}$	-	-	40	mA	
			$V_1 = 0\text{V}$ , $V_2 = 2\text{V}$	-	-	40	mA	
			$V_1 = V_2 = 2\text{V}$	-	-	60	mA	
			$V_1 = V_2 = 0\text{V}$	-	0	-	mA	

**Logic Truth Table**

INPUT		OUTPUT		NOTE
$IN_1$	$IN_2$	$O_1$	$O_2$	
L	L	“OFF” state	“OFF” state	Open
H	L	H	L	Forward
L	H	L	H	Reverse
H	H	L	L	Braking

**Pin Connection Diagram**  
(Front View)

