

# Rochester Electronics Manufactured Components

Rochester branded components are manufactured using either die/wafers purchased from the original suppliers or Rochester wafers recreated from the original IP. All recreations are done with the approval of the OCM.

Parts are tested using original factory test programs or Rochester developed test solutions to guarantee product meets or exceed the OCM data sheet.

#### **Quality Overview**

- ISO-9001
- AS9120 certification
- Qualified Manufacturers List (QML) MIL-PRF-35835
  - Class Q Military
  - Class V Space Level
- Qualified Suppliers List of Distributors (QSLD)
- Rochester is a critical supplier to DLA and meets all industry and DLA standards.

Rochester Electronics, LLC is committed to supplying products that satisfy customer expectations for quality and are equal to those originally supplied by industry manufacturers.

The original manufacturer's datasheet accompanying this document reflects the performance and specifications of the Rochester manufactured version of this device. Rochester Electronics guarantees the performance of its semiconductor products to the original OEM specifications. 'Typical' values are for reference purposes only. Certain minimum or maximum ratings may be based on product characterization, design, simulation, or sample testing.

# Am8T26A·Am8T28

Schottky Three-State Quad Bus Driver/Receiver

#### **Distinctive Characteristics**

- Advanced Schottky technology
- 48mA driver sink current
- Three-state outputs on driver and reciever
- PNP inputs
- Am8T26A has inverting outputs
- Am8T28 has non-inverting outputs

- Driver propagation delay 14ns max. for 8T26A;
   17ns max. for 8T28
- Receiver propagation delay 14ns max. for 8T26A; 17ns max. for 8T28
- 100% reliability assurance testing in compliance with MIL-STD-883

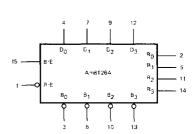
#### **FUNCTIONAL DESCRIPTION**

The Am8T26A/Am8T28 are high speed bus transceivers consisting of four bus drivers with three-state outputs and four bus receivers, also with three-state outputs. Each driver output is internally connected to a receiver input. Both the drivers and receivers have PNP inputs.

One buffered common "bus enable" input is connected to the four drivers and another buffered common "receiver enable" input is connected to the receivers. A LOW on the bus enable (B/E) input forces the four driver outputs to the high-impedance state. A HIGH on the bus enable allows input data to be transferred onto the data bus.

A HIGH on the receiver enable (R/E) input forces the four receiver outputs to the high-impedance state while a LOW on the receiver enable input allows the received data to be transferred to the output. The complementary design of the bus enable and receiver enable inputs allows these control inputs to be connected together externally such that a single transmit/receive function is derived.

#### LOGIC SYMBOL

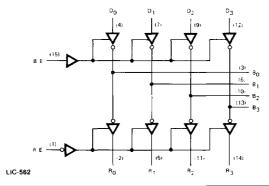


V<sub>CC</sub> = Pin 16 GND = Pin 8

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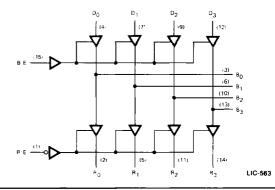
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## Am8T26A Inverting Output (Three-State)



### LOGIC DIAGRAMS

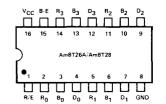
### Am8T28 Non-Inverting Output (Three-State)



#### ORDERING INFORMATION

Package Type	Temperature Range	Am8T26A Order Number	Am8T28 Order Number
Molded DIP	0°C to +75°C	N8T26AB	N8T28B
Hermetic DIP	0°C to +75°C	N8T26AF	N8T28F
Dice	0°C to +75°C	AM8T26AXC	AM8T28XC
Hermetic DIP	-55°C to +125°C	S8T26AF	S8T28F
Dice	-55°C to +125°C	AM8T26AXM	AM8T28XM

#### CONNECTION DIAGRAM (Top View)



Note: Pin 1 is marked for orientation,

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#### MAXIMUM RATINGS (Above which the useful life may be impaired)

Storage Temperature	-65°C to +150°C
Temperature (Ambient) Under Bias	–55°C to +125°C
Supply Voltage to Ground Potential (Pin 16 to Pin 8) Continuous	-0.5V to +7V
DC Voltage Applied to Outputs for HIGH Output State	-0.5V to +V <sub>CC</sub> max.
DC Input Voltage	-0.5V to +5.5V
DC Output Current, Into Outputs (Receiver)	30mA
DC Output Current, Into Outputs (BUS)	80mA
DC Input Current	-30mA to +5.0mA

#### **ELECTRICAL CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE**

The Following Conditions Apply Unless Otherwise Noted:

#### DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE

Parameters	ARACTERISTICS OVER OPERATION  Description		Test Conditions (Note 1)		Typ.	Max.	Units
Driver	Dosonpaon		, con concine (note )	Min.	.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		
I <sub>IL</sub>	Low Level Input Current		V <sub>IN</sub> = 0.4 V			-200	μА
IIL	Low Level Input Current (Disa	bled)	V <sub>IN</sub> = 0.4 V			-25	μА
¹ıн	High Level Input Current (DIN	, D <sub>E</sub> )	V <sub>IN</sub> = V <sub>CC</sub> MAX.			25	ДA
VOL	Low Level Output Voltage		IOUT = 48mA (Note 5)			0.5	Volts
<b>v</b> oH	High Level Output Voltage		I <sub>OUT</sub> = -10mA, V <sub>CC</sub> = V <sub>CC</sub> MIN.(Note 6)	2.4		-	Volts
los	Short Circuit Output Current		V <sub>OUT</sub> = 0V, V <sub>CC</sub> = V <sub>CC</sub> MAX.(Note 4)	-50		150	mA
Receiver							
l <sub>1L</sub>	Low Level Input Current		V <sub>IN</sub> = 0.4 V	_		200	μА
ин	High Level Input Current(RE)		VIN = VCCMAX.			25	μΑ
VOL	Low Level Output Voltage		I <sub>OUT</sub> = 20mA (Note 5)			0.5	Volts
Vou	VOH High Level Output Voltage		I <sub>OUT</sub> = -100 μA, V <sub>CC</sub> = 5.0 V	3.5			Volts
•OH (			I <sub>OUT</sub> = -2.0 mA (Note 6)	2.4			
los	Short Circuit Output Current		VOUT = 0 V, VCC = VCCMAX.	-30		-75	mA
Both Drive	er and Receiver						
V <sub>TL</sub>	Low Level Input Threshold Vo	itage		0.85	1		Voits
V <sub>TH</sub>	High Level Input Threshold Voltage					2.0	Volts
10	Low Level Output Off Leakage Current		V <sub>OUT</sub> ≈ 0.5 V			-100	μА
.	High Level Output Off Leakage Current		V <sub>OUT</sub> ≈ 2.4 V			100	μА
V <sub>I</sub>	Input Clamp Voltage		1 <sub>IN</sub> = -12mA			-1.0	Volts
PWR/	Power/Current Consumption Am8T26A Am8T28		V <sub>CC</sub> = V <sub>CC</sub> MAX.			457/87	mW/mA
Icc			V <sub>CC</sub> = V <sub>CC</sub> MAX.			578/110	] """

Switching Characteristics (T <sub>A</sub> = +25°C, V <sub>CC</sub> = 5.0 V)			Am8T26A			Am8T28				
Parameters	Description	<b>Test Conditions</b>	Min.	Typ.	Max.	Min.	Тур.	Max.	Units	
tPLH	Driver Indiana Bura	m:		10	14		13	17	ns	
tPHL	Driver Input to Bus	rigure i	Figure 1	10	14		13	17		
tPLH	Bus to Receiver Output			9.0	14		12	17	ns	
t <sub>PHL</sub>		Figure 2		6.0	14		9.0	17		
¹ZL	Driver Enable to Bus Fig	Driver Enghla to Bus Figure 2	Figure 3		19	25		21	28	ns
tLZ		rigure 3		15	20		18	23		
tZL	Receiver Enable to	Receiver Enable to Figure 4		15	20		18	23	ns	
<sup>t</sup> LZ	Receiver Output			10	15		13	18	""	

- Notes: 1. For conditions shown as MIN, or MAX., use the appropriate value specified under Electrical Characteristics for the applicable device type.
  - 2. Typical limits are at V<sub>CC</sub> = 5.0 V, 25°C ambient and maximum loading.
  - 3. Actual input currents = Unit Load Current x Input Load Factor (See Loading Rules).
  - 4. Not more than one output should be shorted at a time. Duration of the short circuit test should not exceed one second.
  - 5. Output sink current is supplied through a resistor to V<sub>CC</sub>.
  - 6. Measurements apply to each output and the associated data input independently.

#### **DEFINITION OF FUNCTIONAL TERMS**

 $D_0, D_1, D_2, D_3$  The four driver inputs.

 $\mathbf{B_0}$ ,  $\mathbf{B_1}$ ,  $\mathbf{B_2}$ ,  $\mathbf{B_3}$  The four driver outputs and receiver inputs (data is inverted).

 $R_0$ ,  $R_1$ ,  $R_2$ ,  $R_3$  The four receiver outputs. Data from the bus is inverted while data from the driver inputs is non-inverted.

B/E Bus enable input. When the bus enable input is LOW, the four driver outputs are in the high-impedance state.

**R/E** Receiver enable input. When the receiver enable input is HIGH, the four receiver outputs are in the high-impedance state.

#### LOADING RULES (In Unit Loads)

		LOW	Fan	an-out	
Input/Output	Pin No.'s	Input Unit Load	Output HIGH	Output LOW	
R/E	1	1/8			
R <sub>0</sub>	2	_	50	10	
В <sub>0</sub>	3	1/16	250	25	
D <sub>0</sub>	4	1/8	-	_	
R <sub>1</sub>	5	_	50	10	
B <sub>1</sub>	6	1/16	250	25	
D <sub>1</sub>	7	1/8	_		
GND	8	-	_		
D <sub>2</sub>	9	1/8	_		
B <sub>2</sub>	10	1/16	250	25	
R <sub>2</sub>	11	_	50	10	
D <sub>3</sub>	12	1/8	-	-	
В3	13	1/16	250	25	
R <sub>3</sub>	14		50	10	
~ B/E	15	1/8		_	
v <sub>cc</sub>	16	_	-		

A TTL Unit Load is defined as -1.6 mA measured at 0.4V LOW and  $40 \mu A$  measured at 2.4V HIGH.

#### **DRIVER FUNCTION TABLE**

INPUTS		Am8T26A OUTPUT	Am8T28 OUTPUT	
B/E	Di	Bi	Bį	
L	Х	Z	Z	
н	L	Н	L	
н	Н	L	Н	

L = LOW

X = Don't Care

The second secon

H = HIGH

Z = High Impedance

i = 0, 1, 2, or 3

#### RECEIVER FUNCTION TABLE

INPUTS		Am8T26A OUTPUT	Am8T28 OUTPUT	
R/E	Bi	Ri	Ri	
H	Х	Z	Z	
L	L	н	L	
L	Н	L	Н	

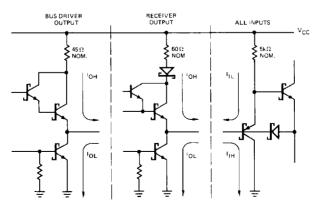
L = LOW

X = Don't Care

H = HIGH Z = High Impedance

i = 0, 1, 2, or 3

#### INPUT/OUTPUT CURRENT INTERFACE CONDITIONS

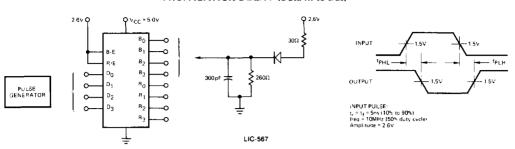


Note: Actual current flow direction shown.

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#### AC TEST CIRCUITS AND WAVEFORMS

#### PROPAGATION DELAY (Data In to Bus)



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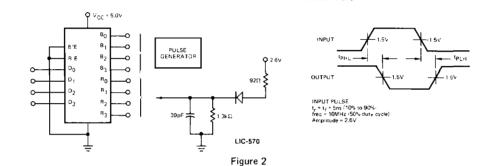
Figure 1

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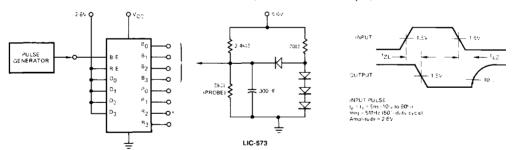
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#### PROPAGATION DELAY (Bus to Receiver Out)



#### PROPAGATION DELAY (Bus Enable to Bus Output)



#### PROPAGATION DELAY- (Receive Enable to Receive Output)

Figure 3

