

# LMC6061 Precision CMOS Single Micropower Operational Amplifier

## **General Description**

The LMC6061 is a precision single low offset voltage, micropower operational amplifier, capable of precision single supply operation. Performance characteristics include ultra low input bias current, high voltage gain, rail-to-rail output swing, and an input common mode voltage range that includes ground. These features, plus its low power consumption, make the LMC6061 ideally suited for battery powered applications.

Other applications using the LMC6061 include precision fullwave rectifiers, integrators, references, sample-and-hold circuits, and true instrumentation amplifiers.

This device is built with National's advanced double-Poly Silicon-Gate CMOS process.

For designs that require higher speed, see the LMC6081 precision single operational amplifier.

For a dual or quad operational amplifier with similar features, see the LMC6062 or LMC6064 respectively.

### PATENT PENDING



- Transducer amplifiers
- Hand-held analytic instruments
- Medical instrumentation
- D/A converter
- Charge amplifier for piezoelectric transducers







	Temperatu	NEC	Transport		
Package	Military −55°C to +125°C	Industrial -40°C to +85°C	Drawing	Media	
8-Pin Molded DIP	LMC6061AMN	LMC6061AIN LMC6061IN	N08E	Rail	
8-Pin Small Outline		LMC6061AIM LMC6061IM	M08A	Rail Tape and Reel	
8-Pin Ceramic DIP	LMC6061AMJ/883		J08A	Rail	

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RRD-B30M75/Printed in U. S. A.

November 1994

100 μV

20 µA

10 fA

140 dB

Absolute Maximum Rati	ngs (Note 1)			
If Military/Aerospace specified dev	ices are required,	Current at Input Pin	±10 mA	
please contact the National Sen	niconductor Sales	Current at Output Pin	$\pm$ 30 mA	
Office/Distributors for availability an	d specifications.	Current at Power Supply Pin	40 mA	
Differential Input Voltage	$\pm$ Supply Voltage	Power Dissipation	(Note 3)	
Voltage at Input/Output Pin	(V+) +0.3V,		(	
	(V <sup>-</sup> ) -0.3V	Operating Ratings (N	ote 1)	
Supply Voltage (V $^+$ – V $^-$ )	16V	Temperature Bange		
Output Short Circuit to V <sup>+</sup>	(Note 10)	LMC6061AM	$-55^{\circ}C \le T_{.1} \le +125^{\circ}C$	
Output Short Circuit to V <sup>-</sup>	(Note 2)	LMC6061AI, LMC6082I	$-40^{\circ}C \le T_J \le +85^{\circ}C$	
Lead Temperature (Soldering, 10 sec.)	260°C	Supply Voltage	$4.5V \leq V^+ \leq 15.5V$	
Storage Temp. Range	-65°C to +150°C	Thermal Resistance ( $\theta_{JA}$ ) (Note 1	1)	
Junction Temperature	150°C	N Package, 8-Pin Molded DIP	115°C/W	
ESD Tolerance (Note 4)	2 kV	M Package, 8-Pin Surface Mour	t 193°C/W	
	2 KV	Power Dissipation	(Note 9)	

**DC Electrical Characteristics** Unless otherwise specified, all limits guaranteed for  $T_J = 25^{\circ}$ C. **Boldface** limits apply at the temperature extremes. V<sup>+</sup> = 5V, V<sup>-</sup> = 0V, V<sub>CM</sub> = 1.5V, V<sub>O</sub> = 2.5V and R<sub>L</sub> > 1M unless otherwise specified.

Symbol	Parameter	Conditions		Typ (Note 5)	LMC6061AM Limit (Note 6)	LMC6061AI Limit (Note 6)	LMC6061I Limit (Note 6)	Units
V <sub>OS</sub>	Input Offset Voltage			100	350 <b>1200</b>	350 900	800 <b>1300</b>	μV Max
TCV <sub>OS</sub>	Input Offset Voltage Average Drift			1.0				μV/°C
IB	Input Bias Current			0.010	100	4	4	pA Max
I <sub>OS</sub>	Input Offset Current			0.005	100	2	2	pA Max
R <sub>IN</sub>	Input Resistance			>10				Tera $\Omega$
CMRR	Common Mode Rejection Ratio	$\begin{array}{l} 0V \leq V_{CM} \leq 12.0V \\ V^+ = 15V \end{array}$		85	75 <b>70</b>	75 <b>72</b>	66 <b>63</b>	dB Min
+ PSRR	Positive Power Supply Rejection Ratio	$5V \le V^+ \le 15V$ $V_0 = 2.5V$		85	75 <b>70</b>	75 <b>72</b>	66 <b>63</b>	dB Min
-PSRR	Negative Power Supply Rejection Ratio	$0V \le V^- \le -10V$		100	84 <b>70</b>	84 <b>81</b>	74 <b>7 1</b>	dB Min
V <sub>CM</sub>	Input Common-Mode Voltage Range	$V^+ = 5V$ and $15V$ for CMRR $\ge 60$ dB		-0.4	-0.1 <b>O</b>	-0.1 <b>O</b>	-0.1 <b>O</b>	V Max
				V <sup>+</sup> - 1.9	V <sup>+</sup> − 2.3 V <sup>+</sup> − 2.6	V <sup>+</sup> − 2.3 V <sup>+</sup> − 2.5	V <sup>+</sup> − 2.3 V <sup>+</sup> − 2.5	V Min
A <sub>V</sub>	Large Signal Voltage Gain	R <sub>L</sub> = 100 kΩ (Note 7)	Sourcing	4000	400 <b>200</b>	400 <b>300</b>	300 <b>200</b>	V/mV Min
			Sinking	3000	180 <b>70</b>	180 <b>100</b>	90 60	V/mV Min
		$R_{L} = 25 \text{ k}\Omega$ (Note 7)	Sourcing	3000	400 <b>150</b>	400 <b>150</b>	200 <b>80</b>	V/mV Min
			Sinking	2000	100 <b>35</b>	100 <b>50</b>	70 35	V/mV Min

Symbol	Parameter	Conditions	Typ (Note 5)	LMC6061AM Limit (Note 6)	LMC6061AI Limit (Note 6)	LMC6061I Limit (Note 6)	Units
VO	Output Swing	$V^+ = 5V$ R <sub>L</sub> = 100 k $\Omega$ to 2.5V	4.995	4.990 <b>4.970</b>	4.990 <b>4.980</b>	4.950 <b>4.925</b>	V Min
			0.005	0.010 <b>0.030</b>	0.010 <b>0.020</b>	0.050 <b>0.075</b>	V Max
		$V^+ = 5V$ $R_L = 25 k\Omega$ to 2.5V	4.990	4.975 <b>4.955</b>	4.975 <b>4.965</b>	4.950 <b>4.850</b>	V Min
			0.010	0.020 <b>0.045</b>	0.020 <b>0.035</b>	0.050 <b>0.150</b>	V Max
		$V^+ = 15V$ $R_L = 100 k\Omega$ to 7.5V	14.990	14.975 <b>14.955</b>	14.975 <b>14.965</b>	14.950 <b>14.925</b>	V Min
			0.010	0.025 <b>0.050</b>	0.025 <b>0.035</b>	0.050 <b>0.075</b>	V Max
		$V^+ = 15V$ $R_L = 25 k\Omega$ to 7.5V	14.965	14.900 <b>14.800</b>	14.900 <b>14.850</b>	14.850 <b>14.800</b>	V Min
			0.025	0.050 <b>0.200</b>	0.050 <b>0.150</b>	0.100 <b>0.200</b>	V Max
lo	Output Current $V^+ = 5V$	Sourcing, $V_O = 0V$	22	16 <b>8</b>	16 <b>10</b>	13 <b>8</b>	mA Min
		Sinking, $V_0 = 5V$	21	16 <b>7</b>	16 <b>8</b>	16 <b>8</b>	mA Min
IO	Output Current V <sup>+</sup> = 15V	Sourcing, $V_O = 0V$	25	15 9	15 <b>10</b>	15 <b>10</b>	mA Min
		Sinking, V <sub>O</sub> = 13V (Note 10)	35	24 7	24 <b>8</b>	24 <b>8</b>	mA Min
IS	Supply Current	$V^+ = +5V, V_0 = 1.5V$	20	24 35	24 <b>32</b>	32 <b>40</b>	μA Max
		$V^+ = +15V, V_0 = 7.5V$	24	30 <b>40</b>	30 <b>38</b>	40 <b>48</b>	μA Max

## AC Electrical Characteristics

Unless otherwise specified, all limits guaranteed for  $T_J = 25^{\circ}$ C, **Boldface** limits apply at the temperature extremes. V<sup>+</sup> = 5V, V<sup>-</sup> = 0V, V<sub>CM</sub> = 1.5V, V<sub>O</sub> = 2.5V and R<sub>L</sub> > 1M unless otherwise specified.

Symbol	Parameter	Conditions	Typ (Note 5)	LMC6061AM Limit (Note 6)	LMC6061AI Limit (Note 6)	LMC6061I Limit (Note 6)	Units
SR	Slew Rate	(Note 8)	35	20 <b>8</b>	20 10	15 <b>7</b>	V/ms Min
GBW	Gain-Bandwidth Product		100				kHz
θm	Phase Margin		50				Deg
e <sub>n</sub>	Input-Referred Voltage Noise	F = 1 kHz	83				nV <i>I</i> √ Hz
i <sub>n</sub>	Input-Referred Current Noise	F = 1 kHz	0.0002				pA∕⁄ Hz
T.H.D.	Total Harmonic Distortion	$ \begin{array}{l} F = 1 \; kHz,  A_V =  -5 \\ R_L =  100 \; k\Omega,  V_O = 2 \; V_{PP} \\ \pm  5 V \; Supply \end{array} $	0.01				%

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but do not guarantee specific performance limits. For guaranteed specifications and test conditions, see the Electrical Characteristics. The guaranteed specifications apply only for the test conditions listed.

Note 2: Applies to both single-supply and split-supply operation. Continous short circuit operation at elevated ambient temperature can result in exceeding the maximum allowed junction temperature of 150°C. Output currents in excess of ±30 mA over long term may adversely affect reliability.

Note 3: The maximum power dissipation is a function of  $T_{J(Max)}$ ,  $\theta_{JA}$ , and  $T_A$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(Max)} - T_A)/\theta_{JA}$ .

Note 4: Human body model, 1.5 k $\Omega$  in series with 100 pF.

Note 5: Typical values represent the most likely parametric norm.

Note 6: All limits are guaranteed by testing or statistical analysis.

Note 7: V<sup>+</sup> = 15V, V<sub>CM</sub> = 7.5V and R<sub>L</sub> connected to 7.5V. For Sourcing tests, 7.5V  $\leq$  V<sub>0</sub>  $\leq$  11.5V. For Sinking tests, 2.5V  $\leq$  V<sub>0</sub>  $\leq$  7.5V.

Note 8: V<sup>+</sup> = 15V. Connected as Voltage Follower with 10V step input. Number specified is the slower of the positive and negative slew rates.

Note 9: For operating at elevated temperatures the device must be derated based on the thermal resistance  $\theta_{JA}$  with  $P_D = (T_J - T_A)/\theta_{JA}$ .

Note 10: Do not connect output to V<sup>+</sup>, when V<sup>+</sup> is greater than 13V or reliability witll be adversely affected.

Note 11: All numbers apply for packages soldered directly into a PC board.

Note 12: For guaranteed Military Temperature Range parameters see RETSMC6061X.





## **Applications Hints**

## AMPLIFIER TOPOLOGY

The LMC6061 incorporates a novel op-amp design topology that enables it to maintain rail-to-rail output swing even when driving a large load. Instead of relying on a push-pull unity gain output buffer stage, the output stage is taken directly from the internal integrator, which provides both low output impedance and large gain. Special feed-forward compensation design techniques are incorporated to maintain stability over a wider range of operating conditions than traditional micropower op-amps. These features make the LMC6061 both easier to design with, and provide higher speed than products typically found in this ultra-low power class.

#### COMPENSATING FOR INPUT CAPACITANCE

It is quite common to use large values of feedback resistance for amplifiers with ultra-low input current, like the LMC6061.

Although the LMC6061 is highly stable over a wide range of operating conditions, certain precautions must be met to achieve the desired pulse response when a large feedback resistor is used. Large feedback resistors and even small values of input capacitance, due to transducers, photodiodes, and circuit board parasitics, reduce phase margins.

When high input impedances are demanded, guarding of the LMC6061 is suggested. Guarding input lines will not only reduce leakage, but lowers stray input capacitance as well. (See *Printed-Circuit-Board Layout for High Impedance Work*).

The effect of input capacitance can be compensated for by adding a capacitor. Place a capacitor,  $C_f$ , around the feedback resistor (as in *Figure 1*) such that:

$$\frac{1}{2\pi R_1 C_{IN}} \geq \frac{1}{2\pi R_2 C_f}$$
 or

$$R_1 C_{IN} \le R_2 C$$

Since it is often difficult to know the exact value of  $C_{\rm IN},\,C_{\rm f}$  can be experimentally adjusted so that the desired pulse response is achieved. Refer to the LMC660 and the LMC662 for a more detailed discussion on compensating for input capacitance.



FIGURE 1. Canceling the Effect of Input Capacitance

#### CAPACITIVE LOAD TOLERANCE

All rail-to-rail output swing operational amplifiers have voltage gain in the output stage. A compensation capacitor is normally included in this integrator stage. The frequency location of the dominate pole is affected by the resistive load on the amplifier. Capacitive load driving capability can be optimized by using an appropriate resistive load in parallel with the capacitive load (see typical curves). Direct capacitive loading will reduce the phase margin of many op-amps. A pole in the feedback loop is created by the combination of the op-amp's output impedance and the capacitive load. This pole induces phase lag at the unity-gain crossover frequency of the amplifier resulting in either an oscillatory or underdamped pulse response. With a few external components, op amps can easily indirectly drive capacitive loads, as shown in *Figure 2a*.



#### FIGURE 2a. LMC6061 Noninverting Gain of 10 Amplifier, Compensated to Handle Capacitive Loads

In the circuit of *Figure 2a*, R1 and C1 serve to counteract the loss of phase margin by feeding the high frequency component of the output signal back to the amplifier's inverting input, thereby preserving phase margin in the overall feedback loop.

Capacitive load driving capability is enhanced by using a pull up resistor to V<sup>+</sup> (*Figure 2b*). Typically a pull up resistor conducting 10  $\mu$ A or more will significantly improve capacitive load responses. The value of the pull up resistor must be determined based on the current sinking capability of the amplifier with respect to the desired output swing. Open loop gain of the amplifier can also be affected by the pull up resistor (see electrical characteristics).



Capacitive Loads with a Pull Up Resistor

#### PRINTED-CIRCUIT-BOARD LAYOUT FOR HIGH-IMPEDANCE WORK

It is generally recognized that any circuit which must operate with less than 1000 pA of leakage current requires special layout of the PC board. When one wishes to take advantage of the ultra-low bias current of the LMC6061, typically less than 10 fA, it is essential to have an excellent layout. Fortunately, the techniques of obtaining low leakages are

### Applications Hints (Continued)

quite simple. First, the user must not ignore the surface leakage of the PC board, even though it may sometimes appear acceptably low, because under conditions of high humidity or dust or contamination, the surface leakage will be appreciable.

To minimize the effect of any surface leakage, lay out a ring of foil completely surrounding the LMC6061's inputs and the terminals of capacitors, diodes, conductors, resistors, relay terminals etc. connected to the op-amp's inputs, as in Figure 3. To have a significant effect, guard rings should be placed on both the top and bottom of the PC board. This PC foil must then be connected to a voltage which is at the same voltage as the amplifier inputs, since no leakage current can flow between two points at the same potential. For example, a PC board trace-to-pad resistance of  $10^{12}\Omega$ , which is normally considered a very large resistance, could leak 5 pA if the trace were a 5V bus adjacent to the pad of the input. This would cause a 100 times degradation from the LMC6061's actual performance. However, if a guard ring is held within 5 mV of the inputs, then even a resistance of  $10^{11}\Omega$  would cause only 0.05 pA of leakage current. See Figures 4a, 4b, 4c for typical connections of guard rings for standard op-amp configurations.



FIGURE 3. Example of Guard Ring in P.C. Board Layout



The designer should be aware that when it is inappropriate to lay out a PC board for the sake of just a few circuits, there is another technique which is even better than a guard ring on a PC board: Don't insert the amplifier's input pin into the board at all, but bend it up in the air and use only air as an insulator. Air is an excellent insulator. In this case you may have to forego some of the advantages of PC board construction, but the advantages are sometimes well worth the effort of using point-to-point up-in-the-air wiring. See *Figure 5*.



## Latchup

CMOS devices tend to be susceptible to latchup due to their internal parasitic SCR effects. The (I/O) input and output pins look similar to the gate of the SCR. There is a minimum current required to trigger the SCR gate lead. The LMC6061 and LMC6081 are designed to withstand 100 mA surge current on the I/O pins. Some resistive method should be used to isolate any capacitance from supplying excess current to the I/O pins. In addition, like an SCR, there is a minimum holding current for any latchup mode. Limiting current to the supply pins will also inhibit latchup susceptibility.

## **Typical Single-Supply** Applications ( $V^+ = 5.0 V_{DC}$ )

The extremely high input impedance, and low power consumption, of the LMC6061 make it ideal for applications that require battery-powered instrumentation amplifiers. Examples of these types of applications are hand-held pH probes, analytic medical instruments, magnetic field detectors, gas detectors, and silicon based pressure transducers.

Figure 6 shows an instrumentation amplifier that features high differential and common mode input resistance  $(>10^{14}\Omega)$ , 0.01% gain accuracy at A<sub>V</sub> = 100, excellent CMRR with 1 k $\Omega$  imbalance in bridge source resistance. Input current is less than 100 fA and offset drift is less than 2.5 µV/°C. R<sub>2</sub> provides a simple means of adjusting gain over a wide range without degrading CMRR. R7 is an initial trim used to maximize CMRR without using super precision matched resistors. For good CMRR over temperature, low drift resistors should be used.









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